

Mock Test:

**ELECTRICAL ENGINEERING  
PAPER-2**

TOTAL QUESTIONS=200

**1. The electric current in a liquid is due to the flow of**

- (i) Electrons only
- (ii) Positive ions only
- (iii) Negative and positive ions both
- (iv) Electrons and positive ions both

**Ans:-** (iii) Negative and positive ions both

**2. Electric current is a**

- (i) Scalar quantity
- (ii) Vector quantity
- (iii) Sometimes scalar and sometimes vector
- (iv) Number only

**Ans:-** (i) Scalar quantity

**3. A pillion electrons pass through a cross-section of a conductor in  $10^{-3}$  s. The current is**

- (i)  $10^{-7}$  A
- (ii)  $1.6 \times 10^{-7}$  A
- (iii)  $2 \times 10^{-4}$  A
- (iv)  $2.6 \times 10^{-3}$  A

**Ans:-** (ii)  $1.6 \times 10^{-7}$  A

**Hints:**  $I = \frac{ne}{t} = \frac{10^9 \times 1.6 \times 10^{-19}}{10^{-3}}$   
 $= 1.6 \times 10^{-7} A$

**4. The electric current in a discharge tube containing a gas is due to**

- (i) Electrons only
- (ii) Positive ions only
- (iii) Negative and positive ions both
- (iv) Electrons and positive ions both

**Ans:-** (iv) Electrons and positive ions both

**5. How long does it, take,  $50 \mu C$  of charge to pass a point in a circuit if the current flow is 15 mA?**

- (i)  $3.33 \times 10^{-3} s$
- (ii)  $6 \times 10^2 s$
- (iii) 2 s
- (iv) None of the above

**Ans:-** (i)  $3.33 \times 10^{-3} s$

**Hints:**  $t = \frac{q}{I} = \frac{50 \times 10^{-6}}{15 \times 10^{-3}}$   
 $= 3.33 \times 10^{-3} s.$

**6. When cells are arranged in parallel**

- (i) The current capacity increases
- (ii) The current capacity decreases
- (iii) The e.m.f. increases
- (iv) The e.m.f. decreases

**Ans:-** (i) The current capacity increases

**7. When a number of resistances are connected in parallel, the total resistance is**

- (i) Greater than the smallest resistance
- (ii) Between the smallest and greatest resistance.

- (iii) Less than the smallest resistance
- (iv) None of the above

**Ans:-** (iii) Less than the smallest resistance

**8. A linear circuit is one whose parameters (e.g. resistances etc.).....**

- (i) Change with change in current
- (ii) Change with change in voltage
- (iii) Do not change with voltage and current
- (iv) None of the above

**Ans:-** (iii) Do not change with voltage and current

**9. Three electric bulbs 40 W, 60 W and 100 W are designed to work on a 220 V mains. Which bulb will burn most brightly if they are connected in series across 220 V mains?**

- (i) 60 W
- (ii) 40 W
- (iii) 100 W
- (iv) All bulbs will bum equally brightly

**Ans:-** (ii) 40 W

**10. As one penetrates a uniformly charged sphere, the electric field strength**

- (i) Increases
- (ii) Decreases
- (iii) Remains the same throughout the space
- (iv) Is zero at all points inside the sphere

**Ans:-** (iv) Is zero at all points inside the sphere

**11. Two charges 4  $\mu\text{C}$  and 7 mC are placed 4.5 cm apart. What is the electric potential energy of the system?**

- (i)  $5.6 \times 10^4 \text{ J}$
- (ii)  $4.2 \times 10^6 \text{ J}$
- (iii)  $5.6 \times 10^3 \text{ J}$
- (iv) None of the above

**Ans:-** (iii)  $5.6 \times 10^3 \text{ J}$

**Hints:**

$$U = \frac{1}{4\pi\epsilon_0} \times \frac{Q_1 Q_2}{d} = 9 \times 10^9 \times \frac{4 \times 10^{-6} \times 7 \times 10^{-3}}{4.5 \times 10^{-2}} = 5.6 \times 10^3 \text{ J.}$$

**12. An electric dipole is placed in a non-uniform electric field. It experiences**

- (i) A force but no torque
- (ii) A force and a torque
- (iii) A torque but no force
- (iv) Neither a force nor a torque

**Ans:-** (ii) A force and a torque

**13. Two point charges are placed on x-axis. A 2  $\mu\text{C}$  charge is at  $x = 10 \text{ cm}$  and  $-1 \mu\text{C}$  charge is at  $x = 40 \text{ cm}$ . What is the potential at  $x = 100 \text{ cm}$  from the origin?**

- (i) 5 V
- (ii) 50V
- (iii) 250 V
- (iv) 5000 V

**Ans:-** (iv) 5000 V

**Hints:**  $V^{100} = 9 \times 10^9 \left[ \frac{2 \times 10^{-6}}{(100-10) \times 10^{-2}} + \frac{-1 \times 10^{-6}}{(100-40) \times 10^{-2}} \right]$   
 $= 5000 \text{ V.}$

**14. Three charges each of +2 C are placed at the three comers of an-equilateral triangle. If the force between any two charges is F, then net force on any charge is**

- (i)  $\sqrt{2}F$       (ii)  $\sqrt{3}F$       (iii)  $2 F$       (iv)  $3 F$

**Ans:-** (ii)  $\sqrt{3}F$

**Hints:** On any charge, two forces, each of magnitude F, are acting. The angle between these equal forces is  $60^\circ$ . Therefore, net force on any charge =  $2F \cos 60^\circ/2 = \sqrt{3} F$ .

**15. Electric lines of force about a negative point charge are**

- (i) Circular clockwise  
(ii) Radial outward  
(iii) Radial inward  
(iv) Circular anticlockwise

**Ans:-** (iii) Radial inward

**16. Three small sized insulated spheres each carrying a charge +q are placed at three points on the circumference of a circle so as to form an equilateral triangle. If R is the radius of the circle, what will be the force on charge +Q placed at the centre of the circle?**

- (i) Zero      (ii)  $\frac{Qq}{4\pi\epsilon_0 R^2}$   
(iii)  $\frac{2Qq}{4\pi\epsilon_0 R^2}$       (iv)  $\frac{3Qq}{4\pi\epsilon_0 R^2}$

**Ans:-** (i) Zero

**Hints:** The charge +Q will be under the action of three equal forces acting outward and displaced from each at angle of  $120^\circ$ . Therefore, the resultant of any two forces is equal and opposite to the third force. As a result, the resultant force on +Q will be zero.

**17. Two charged conducting spheres have radii  $r_1$  and  $r_2$ . The ratio of their charge densities if their potentials are the same is**

- (i)  $r_1^2/r_2^2$       (ii)  $r_2^2/r_1^2$   
(iii)  $r_1 / r_2$       (iv)  $r_2 / r_1$

**Ans:-** (iv)  $r_2 / r_1$

**18. A charge of  $6.75 \mu\text{C}$  in an electric field is acted upon by a force of 2.5 N. The potential gradient at that point is**

- (i)  $4.2 \times 10^6 \text{ V/m}$       (ii)  $3.71 \times 10^5 \text{ V/m}$   
(iii)  $2.9 \times 10^8 \text{ V/m}$       (iv) None of the above

**Ans:-** (ii)  $3.71 \times 10^5 \text{ V/m}$

**19. The potential at a certain point from a point charge is 600 V and the electric field is  $200 \text{ NC}^{-1}$ . The distance of the point of observation from the point charge is**

- (i) 30 m      (ii) 0.3 m  
(iii) 3 m      (iv) 300 m

**Ans:-** (iii) 3 m

**20. In the above question, the magnitude of point charge is**

- (i)  $2 \times 10^{-7} \text{ C}$       (ii)  $3.2 \times 10^{-6} \text{ C}$   
(iii)  $2.9 \times 10^{-8} \text{ C}$       (iv)  $4.2 \times 10^{-6} \text{ C}$

**Ans:-** (i)  $2 \times 10^{-7} \text{ C}$

**21.  $n$  drops each of radius  $r$  and carrying charge  $q$  are combined to form a bigger drop of radius  $R$ . What is the ratio of potentials of bigger to that of the smaller?**

- (i)  $n^{3/2} : 1$       (ii)  $n^{1/3} : 1$   
(iii)  $n^{3/4} : 1$       (iv)  $n^{2/3} : 1$

**Ans:-** (iv)  $n^{2/3} : 1$

**Hints:**  $n \times \frac{4}{3}\pi r^3 = \frac{4}{3}\pi R^3$  or  $R = r n^{2/3}$

Now,  $V_1 \propto q/r$  and  $V_2 \propto n q/R$

$$\therefore \frac{V_2}{V_1} = \frac{nr}{R} = \frac{nr}{n^{1/3} \times r} = \frac{n^{2/3}}{1}$$

**22. A hollow metallic sphere of radius 0.1 m is given a charge of 10  $\mu$ C. The potential on the surface of sphere is**

- (i)  $9 \times 10^3$  V                      (ii)  $9 \times 10^5$  V  
(iii)  $4.5 \times 10^6$  V                (iv)  $3 \times 10^8$  V

**Ans:-** (ii)  $9 \times 10^5$  V

**23. A charge  $3.2 \times 10^{-19}$  C is placed in a uniform electric field of 100 V/m and moves a distance of 0.2 m parallel to and in the direction of field. The energy transformed is**

- (i) 500 J                              (ii) 250 J  
(iii)  $6.4 \times 10^{-18}$  J                (iv)  $6.4 \times 10^{-20}$  J

**Ans:-** (iii)  $6.4 \times 10^{-18}$  J

**Hints:** P.D.,  $V = E \times d = 100 \times 0.2 = 20$  V

Energy transformed = charge  $\times$  p.d. =  $3.2 \times 10^{-19} \times 20 = 6.4 \times 10^{-18}$  J.

**24. The magnitude of electric field that will balance the weight of a-particle will be**

- (i)  $2 \times 10^{-7}$  N/C                    (ii)  $10^{-12}$  N/C  
(iii)  $1.7 \times 10^{-19}$  N/C              (iv)  $5 \times 10^{-6}$  N/C

**Ans:-** (i)  $2 \times 10^{-7}$  N/C

**25. The capacitance of a capacitor is..... relative permittivity.**

- (i) Directly proportional to  
(ii) Inversely proportional to  
(iii) Independent of  
(iv) Directly proportional to square of

**Ans:-** (i) Directly proportional to

**26. An air capacitor has the same dimensions as that of a mica capacitor. If the capacitance of mica capacitor is 6 times that of air capacitor, then relative permittivity of mica is**

- (i) 36                      (ii) 12                      (iii) 3                      (iv) 6

**Ans:-** (iv) 6

**27. When the relative permeability of a material is much greater than 1, it is called**

- (i) Diamagnetic material  
(ii) Paramagnetic material  
(iii) Ferromagnetic material  
(iv) None of the above

**Ans:-** (iii) Ferromagnetic material

**28. The magnetic flux density in an air-cored coil is  $10^{-2}$  Wb/m<sup>2</sup>. With a cast iron core of relative permeability 100 inserted, the flux density will become**

- (i)  $10^{-4}$  Wb/m<sup>2</sup>                      (ii)  $10^4$  Wb/m<sup>2</sup>  
(iii)  $10^{-2}$  Wb/m<sup>2</sup>                    (iv) 1 Wb/m<sup>2</sup>

**Ans:-** (iv) 1 Wb/m<sup>2</sup>

**Hints:**  $\mu_r = \frac{B_{iron}}{B_{air}}$

or  $B_{iron} = \mu_r \times B_{air} = 100 \times 10^{-2} = 1$  Wb/m<sup>2</sup>.

**29. Which of the following is more suitable for the core of an electromagnet?**

- (i) Soft iron
- (ii) Air
- (iii) Steel
- (iv) Tungsten steel

**Ans:-** (i) Soft iron

**30. The source of a magnetic field is**

- (i) An isolated magnetic pole
- (ii) Static electric charge
- (iii) Magnetic substances
- (iv) Current loop

**Ans:-** (iv) Current loop

**31. A magnetic needle is kept in a uniform magnetic field. It experiences**

- (i) A force and a torque
- (ii) A force but not a torque
- (iii) A torque but not a force
- (iv) Neither a torque nor a force

**Ans:-** (iii) A torque but not a force

**32. The unit of pole strength is**

- (i) A/m<sup>2</sup>
- (ii) Am
- (iii) Am<sup>2</sup>
- (iv) Wb/m<sup>2</sup>

**Ans:-** (ii) Am

**33. When the relative permeability of a material is slightly more than 1, it is called**

- (i) Diamagnetic material
- (ii) Paramagnetic material
- (iii) Ferromagnetic material
- (iv) None of the above

**Ans:-** (ii) Paramagnetic material

**34. AT/m is the unit of**

- (i) m.m.f.
- (ii) Reluctance
- (iii) Magnetising force
- (iv) Magnetic flux density

**Ans:-** (iii) Magnetising force

**35. The  $B-H$  curve of..... will not be a straight line.**

- (i) Air
- (ii) Copper
- (iii) Wood
- (iv) Soft iron

**Ans:-** (iv) Soft iron

**Hints:** For a magnetic material,  $B = \mu_0 \mu_r H$

Since  $\mu_r$  is not a constant quantity, the relation between  $B$  and  $H$  is non-linear.

**36. The  $B-H$  curve is used to find the m.m.f. of..... in a magnetic circuit.**

- (i) Air gap
- (ii) Iron part
- (iii) Both air gap and iron part
- (iv) None of the above

**Ans:-** (ii) Iron part

**37. The saturation flux density for most magnetic materials is about.....**

- (i) 0.5 Wb/m<sup>2</sup>
- (ii) 10 Wb/m<sup>2</sup>
- (iii) 2 Wb/m<sup>2</sup>
- (iv) 1 Wb/m<sup>2</sup>

**Ans:-** (iii)  $2 \text{ Wb/m}^2$

**38. Hysteresis is the phenomenon of.....in a magnetic circuit.**

- (i) Lagging of  $B$  behind  $H$
- (ii) Lagging of  $H$  behind  $B$
- (iii) Setting up constant flux
- (iv) None of the above

**Ans:-** (i) Lagging of  $B$  behind  $H$

**39. If a magnetic material is located within a coil through which alternating current (50 Hz frequency) flows, then..... hysteresis loops will be formed every second.**

- (i) 50      (ii) 25      (iii) 100      (iv) 150

**Ans:-** (i) 50

**40. Out of the following materials, the area of hysteresis loop will be least for.....**

- (i) Wrought iron      (ii) Hard steel
- (iii) Silicon steel      (iv) Soft iron

**Ans:-** (iii) Silicon steel

**41. The materials used for the core of a good relay should have..... hysteresis loop.**

- (i) Large      (ii) Very large
- (iii) Narrow      (iv) None of the above

**Ans:-** (iii) Narrow

**42. The magnetic material used for..... should have a large hysteresis loop.**

- (i) transformers      (ii) d.c. generators
- (iii) a.c. motors      (iv) permanent magnets

**Ans:-** (iv) permanent magnets

**Hints:** A large hysteresis loop means high residual flux density and large coercive force. Both these features mean that demagnetising energy required is very large. Therefore, the answer is permanent magnets.

**43. When transformer primary is fed from a.c., its core heats up due to.....**

- (i) permeability of core
- (ii) reluctance of core
- (iii) ferromagnetism
- (iv) hysteresis loss

**Ans:-** (iv) hysteresis loss

**44. Hysteresis loss can be reduced by.....**

- (i) laminating the magnetic circuit
- (ii) using material of narrow hysteresis loop
- (iii) increasing m.m.f. of the circuit
- (iv) none of the above

**Ans:-** (ii) using material of narrow hysteresis loop

**45. The hysteresis loop for materials having high retentivity is**

- (i) Wide
- (ii) Narrow
- (iii) Straight line passing through origin
- (iv) Data insufficient

**Ans:-** (i) Wide

**46. Fringing effect is ignored in a magnetic circuit if air-gap is**

- (i) Large                      (ii) Small  
(iii) Very large              (iv) None of the above

**Ans:-** (ii) Small

**47. An air-cored coil carries steady current. If air-core is replaced by a ferromagnetic material, the flux density in the core will**

- (i) Remain same              (ii) Decrease  
(iii) Increase                (iv) None of the above

**Ans:-** (iii) Increase

**48. Two pure inductors, each of self inductance  $L$ , are connected in parallel but are well separated from each other. Then total inductance is**

- (i)  $L$             (ii)  $2L$             (iii)  $L/4$             (iv)  $L/2$

**Ans:-** (iv)  $L/2$

**49. Two series - opposing inductors have values of 1 H and 1.7 H. What is the total inductance if their mutual inductance is 300 mH?**

- (i) 1 H            (ii) 2 H            (iii) 2.1 H            (iv) 0.5 H

**Ans:-** (iii) 2.1 H

**50. In the above question, what is the coefficient of coupling?**

- (i) 0.5            (ii) 0.1            (iii) 0.26            (iv) 0.23

**Ans:-** (iv) 0.23

**51. A 100 mH coil carries a current of 1A. Energy stored in the magnetic field is**

- (i) 1 J            (ii) 0.05 J            (iii) 1.5 J            (iv) 2.5 J

**Ans:-** (ii) 0.05 J

**52. The mutual inductance between two coils depends upon**

- (i) Medium between the coils only  
(ii) Separation between the coils only  
(iii) Both (i) and (ii)  
(iv) None of above

**Ans:-** (iii) Both (i) and (ii)

**53. When magnet is in motion relative to a coil, an induced e.m.f. is produced. It does not depend upon**

- (i) Resistance of the coil  
(ii) Pole strength of the pole  
(iii) Motion of the magnet  
(iv) Number of turns of the coil

**Ans:-** (i) Resistance of the coil

**54. A metallic ring is attached to the wall of a room. When the north pole of a magnet is brought near the ring, the induced current in the ring is**

- (i) Anticlockwise              (ii) Clockwise  
(iii) Zero                      (iv) Infinite

**Ans:-** (i) Anticlockwise

**55. The normal drawn to the surface of a conductor makes an angle  $\theta$  with the direction of field  $B$ . The flux  $\phi$  passing through area  $A$  is**

- (i)  $\phi = BA$                       (ii)  $\phi = B/A$

(iii)  $\phi = AB \sin \theta$             (iv)  $\phi = AB \cos \theta$

**Ans:-** (iv)  $\phi = AB \cos \theta$

**56. When a magnet is moved with its N-pole towards a closed coil, the nearer end of the coil acts as**

- (i) N-pole
- (ii) S-pole
- (iii) Sometimes N-pole and sometimes S-pole
- (iv) None of the above

**Ans:-** (i) N-pole

**57. Reactive power in an a.c. circuit is**

- (i) measured by a wattmeter
- (ii) the useful power
- (iii) consumed in the circuit
- (iv) a liability on the circuit

**Ans:-** (iv) a liability on the circuit

**58. A 200V, 50Hz inductive circuit takes a current of 10 A, lagging  $30^\circ$ . The inductive reactance of the circuit is.....**

- (i)  $20\Omega$     (ii)  $10\Omega$     (iii)  $17.32\Omega$             (iv)  $16\Omega$

**Ans:-** (ii)  $10\Omega$

**Hints:**  $Z = 200/10 = 20\Omega$  ;

$$X_L = Z \sin \phi = 20 \times \sin 30^\circ = 10\Omega.$$

**59. In an R-L series circuit is a.....**

- (i) R and  $X_L$                     (ii) R and Z
- (iii) Z and  $X_L$                 (iv) none of the above

**Ans:-** (ii) R and Z

**60. Impedance of a.c. circuit is a.....**

- (i) Phasor                        (ii) Vector quantity
- (iii) Scalar quantity        (iv) none of the above

**Ans:-** (iii) Scalar quantity

**61. In a parallel a.c. circuit, if the supply frequency is less than the resonant frequency, then the circuit is.....**

- (i) Inductive                    (ii) Capacitive
- (iii) Resistive                 (iv) None of the above

**Ans:-** (i) Inductive

**62. The Q-factor of a parallel tuned circuit can be increased by.....**

- (i) Increasing circuit resistance
- (ii) Decreasing circuit resistance
- (iii) Decreasing inductance of the circuit
- (iv) None of the above

**Ans:-** (ii) Decreasing circuit resistance

**Hints:**  $Q = \frac{1}{R} \sqrt{\frac{L}{C}}$

Clearly, Q of the circuit can be increased by decreasing R in the inductive branch.



**63. If a parallel resonant circuit is shunted by a resistance, then.....**

- (i) Circuit impedance is decreased
- (ii)  $Q$  of the circuit is increased
- (iii) The gain of the circuit is increased
- (iv) None of the above

**Ans:-** (i) Circuit impedance is decreased

**64. If the resistance in the inductive branch of a parallel resonant circuit is increased, then,.....**

- (i) The circuit impedance is increased
- (ii)  $Q$  of the circuit is increased
- (iii) Selectivity of the circuit is increased
- (iv) Impedance of the circuit is decreased

**Ans:-** (iv) Impedance of the circuit is decreased

**Hints:** At parallel resonance, circuit impedance =  $L/CR$ . If the resistance  $R$  in the inductive branch is increased, circuit impedance will be decreased.

**65. In a parallel  $RC$  circuit with  $R > X_C$ , the phase angle will be.....**

- (i)  $45^\circ$
- (ii) Greater than  $45^\circ$
- (iii)  $90^\circ$
- (iv) Insufficient data

**Ans:-** (ii) Greater than  $45^\circ$

**66. In a parallel  $RC$  circuit, the phase angle is**

- (i)  $\cos^{-1} \frac{R}{Z}$
- (ii)  $\sin^{-1} \frac{Z}{R}$
- (iii)  $\cos^{-1} \frac{R^2}{Z}$
- (iv)  $\cos^{-1} \frac{Z}{R}$

**Ans:-** (iv)  $\cos^{-1} \frac{Z}{R}$

**67. In a parallel  $RL$  circuit,  $I_R = 20$  mA and line current  $I = 18$  mA. The statement is**

- (i) Correct
- (ii) Incorrect
- (iii) Lacking data
- (iv) None of the

**Ans:-** (ii) Incorrect

**Hints:** The statement is incorrect because in a parallel  $RL$  circuit, the line current  $I$  is given by;

$$I = \sqrt{I_R^2 + I_L^2}$$

Therefore, value of  $I$  will be more than  $I_R$  or  $I_L$ .

**68. When it is not appropriate to use the formula  $f_r = 1/2\pi \sqrt{LC}$  for a practical parallel  $LC$  circuit?**

- (i) When  $Q$  of inductor is less than 10
- (ii) When  $Q$  of inductor is more than 10
- (iii) When  $Q$  of inductor is less than 100
- (iv) None of the above

**Ans:-** (i) When  $Q$  of inductor is less than 10

**69. In a practical parallel resonant circuit,**

- (i)  $I_L = I_C$
- (ii)  $I_L > I_C$
- (iii)  $I_L < I_C$
- (iv)  $I_L = 100 I_C$

**Ans:-** (ii)  $I_L > I_C$

**70. In a parallel resonant  $LC$  circuit, the current is**

- (i) Equal to  $I_L$  or  $I_C$
- (ii) Much greater than  $I_L$  or  $I_C$

- (iii) Much less than  $I_L$  or  $I_C$
- (iv) None of the above

**Ans:-** (iii) Much less than  $I_L$  or  $I_C$

**Hints:** In a parallel  $LC$  circuit, the current  $I_C$  or  $I_L$  at resonance is much greater than the line current but  $I_C$  and  $I_L$  are in phase opposition. Therefore, line current is much less than  $I_L$  or  $I_C$ .

**71. The difference between the two half-power frequencies is called.....**

- (i) Resonant frequency
- (ii) Quality factor
- (iii) Mid-frequency
- (iv) Bandwidth

**Ans:-** (iv) Bandwidth

**72. At parallel resonance, the circuit susceptance is**

- (i) Zero
- (ii) Maximum
- (iii) 1
- (iv) Cannot say

**Ans:-** (i) Zero

**Hints:** Resonance is defined as a circuit condition of unity power factor. Under this condition, the circuit admittance is a pure conductance i.e., circuit susceptance is zero.

**73. At parallel resonance, the circuit, admittance is equal to circuit.....**

- (i) Resistance
- (ii) Conductance
- (iii) Susceptance
- (iv) Inductance

**Ans:-** (ii) Conductance

**74. At resonant frequency, the power dissipated in a parallel resonant circuit is  $P$ . The power dissipated at half-power frequencies is**

- (i)  $2P$
- (ii)  $1.5P$
- (iii)  $P/2$
- (iv)  $P/\sqrt{2}$

**Ans:-** (iii)  $P/2$

**Hints:** At half-power frequencies, the power dissipated in the resonant circuit is one-half that dissipated at the resonant frequency.

**75. If  $f_1$  and  $f_2$  are the half-power frequencies in a parallel resonant circuit, then resonant frequency is**

- (i)  $f_2/f_1$
- (ii)  $f_1/f_2$
- (iii)  $\frac{f_1/f_2}{2}$
- (iv)  $\sqrt{f_1/f_2}$

**Ans:-** (iv)  $\sqrt{f_1/f_2}$

**76. The instrument in which springs provide the controlling torque as well as serve to lead current into and out of the operating coil is .....instrument.**

- (i) moving-iron
- (ii) hot-wire
- (iii) permanent-magnet moving coil
- (iv) none of the above

**Ans:-** (iii) permanent-magnet moving coil

**77. If current through the operating coil of a moving-iron-instrument is doubled, the operating force becomes.....**

- (i) two times
- (ii) four times
- (iii) one-half time
- (iv) three times

**Ans:-** (ii) four times

**Hints:** In a moving-iron instrument, the deflecting torque is  $T_d \propto I^2 \dots \dots$  for  $d.c$   
 $\propto I^2_{r.m.s.} \dots \dots$  for  $a.c$

If current is doubled, operating torque is increased four times.

**78. The full-scale deflection current of a moving coil instrument is about.....**

- (i) 50 m A      (ii) 1 A      (iii) 3 A      (iv) 2 A

**Ans:-** (i) 50 m A

**79. For measuring high values of alternating current with a dynamometer ammeter, we use a .....**

- (i) Shunt                                      (ii) Multiplier  
(iii) Potential transformer      (iv) Current transform

**Ans:-** (iv) Current transform

**Hints:** For measuring alternating currents larger than 5 A, shunts are not practicable with a dynamometer ammeter. It is because the division of current between the shunt and the coils varies with frequency (since reactance of coils depends upon frequency). Therefore, the instrument will be accurate only at the frequency at which it is calibrated. Instead we use current transformer.

**80. Hot-wire instrument have ..... scale.**

- (i) Uniform                                      (ii) Log  
(iii) Square                                      (iv) None of the above

**Ans:-** (iii) Square

**81. The full-scale voltage across a moving coil voltmeter is about.....**

- (i) 10 V      (ii) 5 V      (iii) 100 V      (iv) 50 mV

**Ans:-** (iv) 50 mV

**82. Moving-iron instruments have..... scale.**

- (i) uniform      (ii) squared  
(iii) log      (iv) none of the above

**Ans:-** (ii) squared

**83. The range of a moving-iron a.c. ammeter is extended by.....**

- (i) a shunt  
(ii) a multiplier  
(iii) Changing number of turns of operating coil  
(iv) none of the above

**Ans:-** (iii) Changing number of turns of operating coil

**84. To measure high-frequency currents, we mostly use..... ammeter.**

- (i) Hot-wire                                      (ii) Dynamometer  
(iii) Moving-iron                                      (iv) Thermocouple

**Ans:-** (iv) Thermocouple

**85. For the measurement of high direct voltage (say 10 kV), one would use..... voltmeter.**

- (i) Permanent-magnet moving coil  
(ii) Electrostatic  
(iii) Hot-wire  
(iv) Moving iron

**Ans:-** (ii) Electrostatic

**86..... movement is most expensive.**

- (i) D' Arsonval                                      (ii) Moving-iron  
(iii) Dynamometer                                      (iv) None of the above

**Ans:-** (iii) Dynamometer

**87. Electrostatic instruments are used as.....**

- (i) voltmeters only
- (ii) ammeters only
- (iii) both ammeters and voltmeters
- (iv) wattmeters only

**Ans:-** (i) voltmeters only

**88. An electric pyrometer is an instrument used to measure.....**

- (i) phase
- (ii) frequency
- (iii) high temperatures
- (iv) none of the above

**Ans:-** (iii) high temperatures

**89. The best type of meter movement is ..... movement.**

- (i) iron-vane
- (ii) D' Arsonval
- (iii) dynamometer
- (iv) none of the above

**Ans:-** (ii) D' Arsonval

**Hints:** Because it is very light and accurate. Moreover, the sensitivity of the instrument can be greatly increased by increasing the number of turns of the operating coil.

**90. ....instruments are most sensitive.**

- (i) Moving-iron
- (ii) Hot-wire
- (iii) dynamometer
- (iv) Permanent-magnet moving coil

**Ans:-** (iv) Permanent-magnet moving coil

**91. In induction type ammeter,..... damping is provided.**

- (i) air friction
- (ii) eddy current
- (iii) fluid friction
- (iv) none of the above

**Ans:-** (ii) eddy current

**92. The most commonly used induction type instrument is.....**

- (i) induction voltmeter
- (ii) induction wattmeter
- (iii) induction watt-hour meter
- (iv) induction ammeter

**Ans:-** (iii) induction watt-hour meter

**Hints:** The single phase energy meter used in homes is the induction watt-hour meter.

**93. A d.c. compound generator having full-load terminal voltage equal to the no-load voltage is called..... generator.**

- (i) under-compounded
- (ii) over-compounded
- (iii) flat-compounded
- (iv) none of the above

**Ans:-** (iii) flat-compounded

**94. The main drawback of a d.c. shunt generator is that.....**

- (i) terminal voltage drops considerably with load
- (ii) shunt field circuit has high resistance
- (iii) generated voltage is small
- (iv) it is expensive

**Ans:-** (i) terminal voltage drops considerably with load

**95. The terminal voltage of a ..... generator varies widely with changes in load current.**

- (i) series (ii) shunt  
(iii) flat-compounded (iv) none of the above

**Ans:-** (i) series

**96. The effect of armature reaction is to .....**

- (i) decrease the total flux  
(ii) increase the total flux  
(iii) make the air-gap flux uniform  
(iv) none of the above

**Ans:-** (i) decrease the total flux

**97. In a d.c. generator, armature reaction .....pole tip.**

- (i) weakens the flux at the trailing  
(ii) weakens the flux at the leading  
(iii) strengthens the flux at the leading  
(iv) none of the above

**Ans:-** (ii) weakens the flux at the leading

**98. The greatest percentage of heat loss in a d.c machine is due to.....**

- (i) eddy current loss (ii) hysteresis loss  
(iii) copper loss (iv) frictional loss

**Ans:-** (iii) copper loss

**Hint:** The armature current of a d.c. machine is very large. Since **copper loss** is proportional to the square of current, hence a greater part of power loss occurs in the armature.

**99. The size of a d.c. generator can be reduced by using ....**

- (i) lap winding  
(ii) high- resistance winding material  
(iii) iron commutator  
(iv) magnetic material of high permeability

**Ans:-** (iv) magnetic material of high permeability

**100. Hysteresis loss in a d.c machine is directly proportional to.....**

- (i) speed (ii)(speed)<sup>2</sup>  
(iii)(speed)<sup>1.6</sup> (iv) none of the above

**Ans:-** (i) speed

**Hints:** Hysteresis power loss,  $P_h \propto B_{\max}^{1.6} f$

Now  $\phi = NP/120$  so that  $f \propto N(\text{speed})$ . Therefore,  $P_h \propto N$ .

**101. The physical size of 100 kW , 2000 r.p.m. generator is ..... that of 10 kW, 200 r.p.m generator.**

- (i) more than (ii) less than  
(iii) about the same as (iv) none of the above

**Ans:-** (iii) about the same as

**102. ....together are called stray losses.**

- (i) Copper and iron losses
- (ii) Iron and mechanical losses
- (iii) Field copper loss and iron loss
- (iv) Frictional loss and copper loss

**Ans:-** (ii) Iron and mechanical losses

**103. The armature conductors of a 6-pole, lap-wound d.c. generator are divided into.**

- (i) 2 parallel paths
- (ii) 4 parallel paths
- (iii) 3 parallel paths
- (iv) 6 parallel paths

**Ans:-** (iv) 6 parallel paths

**104. The efficiency of a d.c. generator is maximum when its variable loss is**

- (i) equal to constant loss
- (ii) equal to half of constant loss
- (iii) equal to double the constant loss
- (iv) none of the above

**Ans:-** (i) equal to constant loss

**105. A shunt generator delivers 195 A at a terminal p.d. of 250 V. The armature resistance and shunt field resistance are 0.02  $\Omega$  50  $\Omega$  respectively. What is the value of generated e.m.f.?**

- (i) 246 V
- (ii) 254 V
- (iii) 270 V
- (iv) 282 V

**Ans:-** (iii) 254 V

**Hints:**  $I_{sh} = 250/50 = 5 \text{ A} \therefore I_a = I_{sh} + I_L = 5 + 195 = 200 \text{ A}$

Armature drop  $= I_a R_a = 200 \times 0.02 = 4 \text{ V}$

$\therefore$  Generated e.m.f  $= V + I_a R_a = 250 + 4 = 254 \text{ V}$

**106. In the above question, what is the value of copper losses?**

- (i) 825 W
- (ii) 2050 W
- (iii) 1025 W
- (iv) 960 W

**Ans:-** (ii) 2050 W

**Hints:** Armature

Cu loss  $= I_a^2 R_a = (200)^2 \times 0.02 = 800 \text{ W}$

Shunt Cu loss  $= V I_{sh} = 250 \times 5 = 1250 \text{ W}$

Total Cu loss  $= 1250 + 800 = 2050 \text{ W}$

**107. If  $W_C$  is the constant loss and  $R_a$  is the armature resistance of a d.c. generator, then load current  $I_L$  corresponding to maximum efficiency is**

- (i)  $I_L = \sqrt{\frac{R_a}{W_C}}$
- (ii)  $I_L = \frac{W_C}{\sqrt{R_a}}$
- (iii)  $I_L = \frac{R_a}{\sqrt{W_C}}$
- (iv)  $I_L = \sqrt{\frac{W_C}{R_a}}$

**Ans:-** (iv)  $I_L = \sqrt{\frac{W_C}{R_a}}$

**Hints:** The efficiency of a d.c. generator is maximum when Variable loss = Constant loss

Or  $I_L^2 R_a = W_C$  Or  $I_L = \sqrt{\frac{W_C}{R_a}}$

**108. If the flux per pole of a d.c. generator is halved but its speed is doubled, its generated e.m.f. will**

- (i) be halved
- (ii) remain the same
- (iii) be doubled
- (iv) be quadrupled

**Ans:-** (ii) remain the same

**109. In very large d.c. motors with severe heavy duty, armature reaction effects are corrected by.....**

- (i) using interpoles only
- (ii) using compensatory windings in addition to interpoles
- (iii) shifting the brush position
- (iv) none of the above

**Ans:-** (ii) using compensatory windings in addition to interpoles

**Hints:** Some large d.c. motors employed in steel mills perform a series of heavy-duty operations. They accelerate, decelerate, stop, reverse all in a matter of seconds. The corresponding armature current increases, decreases, reverses in stepwise fashion, producing very sudden changes in armature reaction. For such motors, interpoles do not adequately neutralise the armature m.m.f. To eliminate this problem, additional compensating windings are connected in series with the armature. They are distributed in slots, cut into the pole faces of the main field poles. Like interpoles, these windings produce an m.m.f equal and opposite to the m.m.f. of the armature.

**110. The speed of a .....motor is practically constant.**

- (i) cumulatively compounded
- (ii) series
- (iii) differentially compounded
- (iv) shunt

**Ans:-** (iv) shunt

**111. ....motor is variable speed motor.**

- (i) series
- (ii) Shunt
- (iii) Cumulatively compounded
- (iv) Differentially compounded

**Ans:-** (i) series

**112. The most commonly used method of speed control of a d.c. motor is by varying.....**

- (i) voltage applied to the motor
- (ii) field strength
- (iii) effective number of conductors in series
- (iv) armature circuit resistance

**Ans:-** (ii) field strength

**Hints:** The fact that the speed of a d.c. motor varies with field excitation provides a convenient means for controlling the speed of shunt and compound motors.

**113. The running speed of a d.c. series motor is basically determined by.....**

- (i) field excitation
- (ii) load
- (iii) armature resistance
- (iv) none of the above

**Ans:-** (ii) load

**114. After a shunt motor is up to speed, the speed may be increased considerably by .....**

- (i) increasing field circuit resistance
- (ii) decreasing field circuit resistance
- (iii) increasing armature circuit resistance
- (iv) reducing the load

**Ans:-** (ii) decreasing field circuit resistance

**115.....motor has the best speed regulation.**

- (i) Series
- (ii) Cumulatively compounded
- (iii) Shunt
- (iv) Differentially compounded

**Ans:-** (iii) Shunt

**116. The deciding factor in the selection of a d.c. motor for a particular application is its .....characteristic.**

- (i) speed-torque
- (ii) speed-armature current
- (iii) torque-armature current
- (iv) none of the above

**Ans:-** (i) speed-torque

**117. The demand for a large increase in torque of a d.c. shunt motor is met by a.....**

- (i) large decrease in speed
- (ii) large increase in speed
- (iii) large increase in current
- (iv) small increase in current

**Ans:-** (iii) large increase in current

**Hints:** For a d.c. motor,  $T_a \propto \phi I_a$ . But in a shunt motor,  $\phi$  is practically constant so that  $T_a \propto I_a$ . If torque is doubled, armature current is also doubled.

**118. A series motor will over speed when .....**

- (i) the load is increased
- (ii) the field is opened
- (iii) the armature circuit is opened
- (iv) the load is removed

**Ans:-** (iv) the load is removed

**119. A transformer will work on.....**

- (i) a.c. only
- (ii) d.c. only
- (iii) a.c. as well as d.c
- (iv) none of the above

**Ans:-** (i) a.c. only

**Hints:** Transformer action demands only the existence of alternating flux linking the two windings. Since alternating flux can be produced by a.c a transformer will work only on a.c.

**120. The primary and secondary of a transformer are .....coupled.**

- (i) electrically
- (ii) magnetically
- (iii) electrically and magnetically
- (iv) none of the above

**Ans:-** (ii) magnetically



**121. A transformer is an efficient device because it.....**

- (i) is a static device
- (ii) uses inductive coupling
- (iii) uses capacitive coupling
- (iv) uses electric coupling

**Ans:-** (i) is a static device

**Hints:** Since transformer is a static device, the friction and wind age losses are absent.

**122. A transformer transfers electrical energy from primary to secondary usually with a change in.....**

- (i) frequency
- (ii) power
- (iii) voltage
- (iv) time period

**Ans:-** (iii) voltage

**123. The voltage per turn of the primary of a transformer is..... the voltage per turn of the secondary.**

- (i) more than
- (ii) less than
- (iii) the same as
- (iv) none of the above

**Ans:-** (iii) the same as

**Hints:** Since the same mutual flux links both the windings, the voltage per turn of the primary is the same as the voltage per turn of the secondary.

**124. The winding of the transformer with greater number of turns will be.....**

- (i) high-voltage winding
- (ii) low-voltage winding
- (iii) either high or low voltage winding
- (iv) none of the above

**Ans:-** (i) high-voltage winding

**125. A transformer does not possess .....changing property.**

- (i) impedance
- (ii) voltage
- (iii) current
- (iv) power

**Ans:-** (iv) power

**Hints:** A transformer is not a source of energy; it merely transfers power from primary to secondary with a change of voltage /current.

**126. The iron-core is used to ..... of the transformer.**

- (i) increase the weight
- (ii) provide tight magnetic coupling
- (iii) reduce core losses
- (iv) none of the above

**Ans:-** (ii) provide tight magnetic coupling

**Hints:** Iron core ensures tight magnetic coupling between the two windings. The co-efficient of coupling between the winding of a practical transformer may be as high as 0.99

**127. If a transformer core has air gaps, then.....**

- (i) reluctance of magnetic path is decreased
- (ii) hysteresis loss is decreased
- (iii) magnetising current is greatly increased
- (iv) eddy current is increased

**Ans:-** (iii) magnetising current is greatly increased

**128. The maximum flux produced in the core a transformer is .....**

- (i) directly proportional to supply frequency
- (ii) inversely proportional to supply frequency
- (iii) inversely proportional to primary voltage
- (iv) none of the above

**Ans:-** (ii) inversely proportional to supply frequency

**Hints:** The voltage equation of a transformer is given by;

$$V_1 = 4.44 N_1 \phi_{\max} f$$

where  $V_1$  = applied primary voltage;

$N_1$  = number of primary turns

$$\phi_{\max} = \frac{V_1}{4.44 N_1 f}$$

Clearly, maximum flux produced in a core is inversely proportional to supply frequency.

**129. The flux in the core of a single-phase transformer is .....**

- (i) purely alternating one
- (ii) purely rotating one
- (iii) partly alternating and partly rotating
- (iv) none of the above

**Ans:-** (i) purely alternating one

**130. A transformer is so designed that primary and secondary have .....**

- (i) high leakage reactance
- (ii) large resistance
- (iii) tight magnetic coupling
- (iv) good electric coupling

**Ans:-** (iii) tight magnetic coupling

**131. When the primary of a transformer is connected to a d.c. supply, .....**

- (i) primary draws small current
- (ii) primary leakage reactance is increased
- (iii) core losses are increased
- (iv) primary may burn out

**Ans:-** (iv) primary may burn out

**132. The resistance split-phase induction motor are the most popular single-phase motors because of \_\_\_\_\_**

- (i) their low cost
- (ii) their high starting torque
- (iii) the long starting period
- (iv) none of the above

**Ans:-** (i) their low cost

**133. At starting, the-line current of a capacitor-start induction motors is \_\_\_\_\_ the normal full-load current.**

- (i) 8 to 10 times
- (ii) 4 to 5 times
- (iii) equal to
- (iv) 7 to 8 times

**Ans:-** (ii) 4 to 5 times

**134. In a capacitor-start, capacitor-run motor, \_\_\_\_\_ winding is cut out after starting.**

- (i) starting
- (ii) main
- (iii) neither starting nor main
- (iv) none of the above

**Ans:-** (iii) neither starting nor main

**135. A capacitor-start, capacitor-run motor has \_\_\_\_\_**

- (i) low power factor
- (ii) high power factor
- (iii) low efficiency
- (iv) high starting torque

**Ans:-** (ii) high power factor

**Hints:** The capacitor-start, capacitor-run motor is similar to the capacitor-start type except that the starting winding remains in the circuit after the motor is started. Consequently, such a motor operates at a highly power factor.

**136. The capacitor-start, capacitor-run induction motor acts as a true 2-phase motor at \_\_\_\_\_.**

- (i) starting
- (ii) no-load
- (iii) all loads
- (iv) full-load

**Ans:-** (iv) full-load

**137. The capacitor-start, capacitor-run motor is used in those applications where \_\_\_\_\_.**

- (i) high starting torque is required
- (ii) silence is important
- (iii) noisy operation is not important
- (iv) none of the above

**Ans:-** (ii) silence is important

**138. The capacitor-start, capacitor-run motor has \_\_\_\_\_.**

- (i) no centrifugal switch
- (ii) low power factor
- (iii) noisy operation
- (iv) low efficiency

**Ans:-** (i) no centrifugal switch

**139. Capacitor motors \_\_\_\_\_ resistance split-phase induction motors.**

- (i) are costlier than
- (ii) are less costly than
- (iii) cost about the same as
- (iv) have poor starting torque than

**Ans:-** (i) are costlier than

**140. Most of the troubles of single phase induction motors are traceable to the \_\_\_\_\_.**

- (i) rotor bars
- (ii) main winding
- (iii) shaft bearings
- (iv) starting switch

**Ans:-** (iv) starting switch

**141. The single phase shaded pole motor has \_\_\_\_\_**

- (i) squirrel cage rotor
- (ii) wound rotor
- (iii) high power factor
- (iv) high starting torque

**Ans:-** (i) squirrel cage rotor

**142. The direction of rotation of shaded-pole motor depends upon \_\_\_\_\_.**

- (i) supply frequency
- (ii) number of poles on the stator
- (iii) which half of the pole is shaded
- (iv) supply voltage

**Ans:-** (iii) which half of the pole is shaded

**143. The full-load efficiency of a shaded pole motor is about \_\_\_\_\_.**

- (i) 70 to 80%                      (ii) 60 to 70%  
(iii) 30 to 35%                    (iv) 5 to 10%

**Ans:-** (iii) 30 to 35%

**Hints:** The shading coils are not opened after the motor is running at normal speed. Therefore, considerable power loss takes place in the shading coils. For this reason, the efficiency of such a motor is very low, 30 to 35%.

**144. The single phase series motor can operate on \_\_\_\_\_.**

- (i) a.c. only                              (ii) d.c. only  
(iii) both a.c. and d.c.                (iv) none of the above

**Ans:-** (iii) both a.c. and d.c.

**145. For the same rating, a d.c. series motor \_\_\_\_\_ costs single phase series motor.**

- (i) about the same as                (ii) more than  
(iii) less than                            (iv) none of the above

**Ans:-** (iii) less than

**Hints:** The sparking at the brushes of an a.c. series motor is caused by the voltage induced by the alternating main field in the coils short-circuit by the brushes during commutation period. To reduce sparking in an a.c. series motor, the number of turns in each armature coil is kept small and high-resistance leads connect each coil to the commutator segments. As a result, the armature winding of an a.c. series motor has more coils and, therefore, more commutator segments than a comparable d.c. series motor. For this reason, a d.c. series motor costs less than the comparable a.c. series motor.

**146. A vacuum cleaner employs \_\_\_\_\_ motor.**

- (i) resistance split-phase  
(ii) capacitor-start  
(iii) shaded-pole  
(iv) single-phase, series

**Ans:-** (iv) single-phase, series

**147. An alternator is sometimes called \_\_\_\_\_ generator.**

- (i) synchronous                      (ii) asynchronous  
(iii) Rosenberg                        (iv) none of the above

**Ans:-** (i) synchronous

**148. A turbo-alternator uses \_\_\_\_\_**

- (i) salient -pole field structure  
(ii) nonsalient – pole field structure  
(iii) rotating a.c. armature winding  
(iv) none of the above

**Ans:-** (ii) nonsalient – pole field structure

**Hints:-** High-speed or turbo-alternators have non salient – pole (i.e. cylindrical rotor) rotor to withstand the stresses at high speeds. Because the rotor is driven at a high speed, we require a small number of poles.

**149. The non salient-pole field construction is used for \_\_\_\_\_ alternator.**

- (i) low-speed                            (ii) medium-speed  
(iii) high-speed                        (iv) none of the above

**Ans:-** (iii) high-speed

**150. The a.c. armature winding of an alternator is \_\_\_\_\_**

- (i) always star-connected .
- (ii) generally delta-connected
- (iii) star-delta connected
- (iv) none of the above

**Ans:-** (i) always star-connected

**151. Low-speed alternators are driven by \_\_\_\_\_**

- (i) hydraulic turbines
- (ii) steam engines
- (iii) steam turbines
- (iv) none of the above

**Ans:-** (i) hydraulic turbines

**152. High-speed alternators are driven by \_\_\_\_\_**

- (i) diesel engines
- (ii) hydraulic turbines
- (iii) steam turbines
- (iv) none of the above

**Ans:-** (iii) steam turbines

**Hints:-** Steam turbines are smaller and more efficient when they turn at high speed. The same is true of alternators.

**153. The air-gap in an alternator is \_\_\_\_\_ in an induction machine.**

- (i) much shorter than
- (ii) much longer than
- (iii) about the same as
- (iv) none of the above

**Ans:-** (ii) much longer than

**154. The stator of an alternator is wound for \_\_\_\_\_ on the rotor.**

- (i) more number of poles than
- (ii) less number of poles than
- (iii) the same number of poles as
- (iv) none of the above

**Ans:-** (iii) the same number of poles as

**155. The synchronous reactance of an alternator \_\_\_\_\_ as the iron is saturated.**

- (i) decreases
- (ii) increases
- (iii) remains unchanged
- (iv) none of the above

**Ans:-** (i) decreases

**156. In an alternator, the effect of armature reaction is minimum at power factor of \_\_\_\_\_**

- (i) 0.866 lagging
- (ii) 0.866 leading
- (iii) 0.5 lagging
- (iv) unity

**Ans:-** (iv) unity

**157. The lagging load p.f. of an alternator is decreased, the demagnetising effect of armature reaction \_\_\_\_\_**

- (i) remains the same
- (ii) is decreased
- (iii) is increased
- (iv) none of the above

**Ans:-** (iii) is increased

**158. When load on an alternator is increased, the terminal voltage increases if the load p.f. is \_\_\_\_\_**

- (i) unity
- (ii) lagging.
- (iii) leading
- (iv) zero

**Ans:-** (iii) leading

**159. The rotor of a synchronous motor is.....**

- (i) Salient-pole type
- (ii) Nonsalient-pole type
- (iii) Identical to that of a d.c. motor
- (iv) None of the above

**Ans:-** (i) Salient-pole type

**160. Damper winding in a synchronous motor \_\_\_\_\_**

- (i) reduces windage losses
- (ii) serves to reduce motor speed
- (iii) improves p.f. of the motor
- (iv) increases hunting of the motor

**Ans:-** (ii) serves to reduce motor speed

**161. Small synchronous motors are started by \_\_\_\_\_**

- (i) pony motor
- (ii) damper winding
- (iii) variable-frequency source
- (iv) none of the above

**Ans:-** (ii) damper winding

**162. A synchronous motor runs at speeds ranging from \_\_\_\_\_**

- (i) 1800 to 3600 r.p.m.
- (ii) 3600 to 6000 r.p.m.
- (iii) 150 to 1800 r.p.m.
- (iv) none of the above

**Ans:-** (iii) 150 to 1800 r.p.m.

**Hints:-** Most synchronous motors are rated between 150 kW (200 h.p.) and 15 MW (20,000 h.p.) and turn at speeds ranging from 150 to 1800 r.p.m. Consequently, these machines are used in heavy industry.

**163. The full-load slip of a synchronous motor**

**is \_\_\_\_\_**

- (i) 5%
- (ii) 1%
- (iii) 2%
- (iv) zero

**Ans:-** (iv) zero

**Hints:-** A synchronous motor runs at one speed only i.e. synchronous speed. Consequently, slip is zero.

**164. A 50 Hz synchronous motor runs at 200 r.p.m. The number of salient poles on the rotor are \_\_\_\_\_**

- (i) 36
- (ii) 16
- (iii) 30
- (iv) none of the above

**Ans:-** (iii) 30

**165. If the supply frequency of synchronous motors is 60 cycles/second, then the rotor must revolve at \_\_\_\_\_**

- (i) 25 cycles/second
- (ii) 60 cycles/second
- (iii) 100 cycles/second
- (iv) none of the above

**Ans:-** (ii) 60 cycles/second

**Hints:-** The primary requirement is that frequency of rotation of the rotor should be such that stator and rotor fields are stationary with respect to each other. For this to happen, obviously, the rotor must revolve at 60 cycles/second.

**166. A synchronous motor is a \_\_\_\_\_ motor.**

- (i) variable p.f.
- (ii) variable speed
- (iii) singly fed
- (iv) none of the above

**Ans:-** (i) variable p.f.

**167. The rotor of a synchronous motor is excited with direct current when the motor**

- \_\_\_\_\_
- (i) is at standstill (i.e. at starting)
  - (ii) approaches synchronous speed
  - (iii) approaches half synchronous speed
  - (iv) none of the above

**Ans:-** (ii) approaches synchronous speed

**168. When the synchronous motor runs at synchronous speed, the voltage induced in the damper winding is \_\_\_\_\_**

- (i) maximum
- (ii) minimum
- (iii) zero
- (iv) none of the above

**Ans:-** (iii) zero

**Hints:-** When the motor runs at synchronous speed, there is no relative motion between rotor and revolving flux produced by stator currents. Hence e.m.f. in the damper winding placed on the rotor is zero.

**169. In order to reverse the direction of a synchronous motor, \_\_\_\_\_**

- (i) interchange any two stator lines
- (ii) reduce d.c. field excitation to zero
- (iii) change supply frequency
- (iv) none of the above

**Ans:-** (i) interchange any two stator lines

**170. A synchronous motor runs at only one speed (i.e. synchronous speed) because it**

- \_\_\_\_\_
- (i) has no losses
  - (ii) is a doubly fed machine
  - (iii) has a damper winding
  - (iv) none of the above

**Ans:-** (ii) is a doubly fed machine

**Hints:-** The significant and distinguishing feature of synchronous motors in contrast to induction motors is that they are doubly fed. Electrical energy is supplied both to the field and the armature windings. When this is done, torque can only be developed at one speed-the synchronous speed. At any other speed, the torque is zero. In fact, it is this characteristic (i.e. doubly fed) which enables the synchronous motor to develop non-zero torque at only one speed (i.e. synchronous speed) and hence the name synchronous motor.

171. A thermal station has a maximum demand of 20,000. kW and a load factor of 40%.

Units generated per annum will be

- (i)  $525 \times 10^4$  kWh                      (ii)  $105 \times 10^5$  kWh    (iii)  $7008 \times 10^4$  kWh                      (iv)  $62 \times 10^6$  kWh

Ans:- (iii)  $7008 \times 10^4$  kWh

Hints: Units generated/annum

$$\begin{aligned} &= \text{Max.demand} \times \text{L.F.} \times \text{Hours in a year} \\ &= 20,000 \times 0.4 \times 8760 = 7008 \times 10^4 \text{ kWh} \end{aligned}$$

172. The highest point on the daily load curve represents

- (i) average demand  
(ii) maximum demand  
(iii) load factor  
(iv) none of the above

Ans:- (ii) maximum demand

173. The load factor (L.F.), maximum demand (M.D.), average load (A.L.) are related as:

- (i)  $\text{L.F.} = \frac{\text{A.L.}}{\text{M.D.}}$                       (ii)  $\text{L.F.} = \text{A.L.} \times \text{M.D.}$   
(iii)  $\text{L.F.} = \frac{\text{M.D.}}{\text{A.L.}}$                       (iv)  $\text{L.F.} = \text{M.D.}$

Ans:-(i)  $\text{L.F.} = \frac{\text{A.L.}}{\text{M.D.}}$

174. A generating station has a connected load of 43 MW and a maximum demand of 20 MW; the units generated being  $61.5 \times 10^6$  kWh per annum. The demand factor is

- (i) 0.823                      (ii) 0.756  
(iii) 0.465                      (iv) 0.356

Ans:- (iii) 0.465

Hints: Demand factor =  $\frac{\text{Max. demand}}{\text{Connected load}}$   
 $= \frac{20}{43} = 0.465.$

175. In the above question, what is the load factor?

- (i) 35.1%                      (ii) 46.5%    (iii) 78.2%    (iv) 69.5%

Ans:- (i) 35.1%

Hints: Average demand =  $\frac{\text{Units generated/annum}}{\text{Hours in a year}}$   
 $= \frac{61.5 \times 10^6}{8760} = 7020$  kW

$$\begin{aligned} \therefore \text{Load factor} &= \frac{\text{Average demand}}{\text{Max. demand}} = \frac{7020}{20 \times 10^3} \\ &= 0.351 \text{ or } 35.1\% \end{aligned}$$

176. A generating station has an average demand of 15 MW. If the plant capacity factor is 50%, what is the plant capacity?

- (i) 20 MW                      (ii) 10 MW  
(iii) 25 MW                      (iv) 30 MW

Ans:- (iv) 30 MW

Hints: Plant capacity factor =  $\frac{\text{Average demand}}{\text{Plant capacity}}$   
 $\therefore \text{Plant capacity} = \frac{\text{Average demand}}{\text{Plant capacity factor}}$   
 $= \frac{15}{0.5} = 30$  MW



**177. In the above question if the load factor is 60%, what is the reserve capacity of the plant?**

- (i) 30 MW                      (ii) 5 MW  
(iii) 27.5 MW                (iv) 12 MW

**Ans:-** (ii) 5 MW

**Hints:** Maximum demand =  $\frac{\text{Average demand}}{\text{Load factor}}$   
 $= \frac{15}{0.6} = 25 \text{ MW}$

$\therefore$  Reserve capacity of plant  
= Plant capacity – Max. demand  
= 30 – 25 = 5 MW.

**178. The demand factor is generally**

- (i) less than 1                (ii) more than 1  
(iii) equal to 1              (iv) none of the above

**Ans:-** (i) less than 1

**Hints:** The value of demand factor is usually less than 1. It is expected because maximum demand power station is generally less than the connected load.

**179. The load factor is generally**

- (i) more than 1              (ii) less than 1  
(iii) equal to 1              (iv) none of the above

**Ans:-** (ii) less than 1

**Hints:** Load factor =  $\frac{\text{Average demand}}{\text{Max. demand}}$

The load factor is always less than 1 because the average load is smaller than the maximum demand.

**180. The diversity factor is always**

- (i) equal to 1                (ii) less than 1  
(iii) greater than 1        (iv) none of the above

**Ans:-** (iii) greater than 1

**Hints:** Diversity factor =  $\frac{\text{Sum of individual max.demands}}{\text{Max.demand on power station}}$

A power station load to various types of consumers whose maximum demands generally do not occur at the same time. Therefore, the maximum demand on the power station is always less than the sum of individual maximum demands of the consumers. For this reason, diversity factor is always greater than 1.

**181. If the maximum demand on the plant is equal to the plant capacity, then the value of load factor**

- (i) equal to plant capacity factor  
(ii) is less than plant capacity factor  
(iii) is more than plant capacity factor  
(iv) none of the above

**Ans:-** (i) equal to plant capacity factor

**182. If the load factor of a power station increases, the cost per unit generated will**

- (i) increase                    (ii) decrease  
(iii) remain same            (iv) data incomplete

**Ans:-** (ii) decrease

**183. If the diversity factor increases, the maximum demand on power station**

- (i) remains same            (ii) increases
- (iii) decreases            (iv) none of the above

**Ans:-** (iii) decreases

**184. When the load factor of a power station increases, the units (kWh) generated**

- (i) Are increased            (ii) Are decreased
- (iii) Remain the same        (iv) None of above

**Ans:-** (i) Are increased

**Hint:-** Units generated/day = Max.demand (kW) × L.F × 24 hours

The higher the load factor (L.F), the greater is the number of units generated.

**185. The fixed cost of energy generated**

- (i) Depends on maximum demand
- (ii) Depends on units generated
- (iii) Is independent of (i) and (ii)
- (iv) None of the above

**Ans:-** (iii) Is independent of (i) and (ii)

**186. A consumer who consumes more electrical energy should pay**

- (i) More fixed charges per unit
- (ii) Less fixed charges per unit
- (iii) Less running charges per unit
- (iv) None of the above

**Ans:-** (ii) Less fixed charges per unit

**187. The drawback of diminishing value method for calculating depreciation is that depreciation charges**

- (i) Are small in early years
- (ii) Are high in later years
- (iii) Are independent of rate of interest
- (iv) None of the above

**Ans:-** (iii) Are independent of rate of interest

**188. The most fundamental method for calculating the depreciation of equipment is**

- (i) Straight line method
- (ii) Diminishing value method
- (iii) Sinking fund method
- (iv) None of the above

**Ans:-** (iii) Sinking fund method

**189. An ideal value of power factor is**

- (i) 1    (ii) 0.5            (iii) 0.8            (iv) 0.75

**Ans:-** (i) 1

**190. The lagging reactive power drawn load is zero. The power factor of the load is,**

- (i) 0.5    (ii) 0.75            (iii) 1    (iv) None of the

**Ans:-** (iii) 1

**191. Alternators and transformers are rated in**

- (i) kVA    (ii) kW    (iii) kVAR    (iv) none of the above

**Ans:-** (i) kVA

**192. The most economical power factor for a consumer is generally**

- (i) 0.95 lagging                      (ii) 1  
(iii) 0.6 lagging                      (iv) 0.75 lagging

**Ans:-** (i) 0.95 lagging

**193. The correct relation in the following is:**

- (i) kVAR = kW sin  $\phi$       (ii) kVAR = kW tan  $\phi$   
(iii) kVAR = kW cos  $\phi$       (iv) None of the above

**Ans:-** (ii) kVAR = kW tan  $\phi$

Hint:- kVAR = V1 sin  $\phi$  = KVA sin  $\phi$

kW = V1 cos  $\phi$  = kVA cos  $\phi$

$$\therefore \frac{\text{kVAR}}{\text{kW}} = \tan \phi \text{ or } \text{kVAR} = \text{kW} \tan \phi$$

**194. When the power factor is increased,**

- (i) Active power increases  
(ii) Active power decreases  
(iii) Line current increases  
(iv) Line current decreases

**Ans:-** (iv) Line current decreases

Hint:-  $I_L = \frac{P}{V_L \cos \phi}$  .... For single-phase supply

$$I_L = \frac{P}{\sqrt{3} V_L \cos \phi} \text{ ... For 3-phase supply}$$

For fixed P and  $V_L$ , the line current is inversely proportional to the power factor.

**195. Improving the power factor means making it**

- (i) Close to unity                      (ii) Zero  
(iii) Less than 0.5                      (iv) None of the above

**Ans:-** (i) Close to unity

**196. When power factor is improved, the lagging kVAR drawn from the supply will**

- (i) Increase                      (ii) Decrease  
(iii) Remain the same      (iv) None of the above

**Ans:-** (ii) Decrease

**197. A load takes a current of  $I$  at a p.f. of  $\cos \phi$ . The wattless component of current is**

- (i)  $I \cos \phi$                       (ii)  $I \sin \phi$   
(iii)  $I \tan \phi$                       (iv) None of the above

**Ans:-** (ii)  $I \sin \phi$

**198. In order to improve p.f. in case of 3-phase loads, the capacitors are connected in**

- (i) Star                      (ii) Delta  
(iii) Star or delta                      (iv) None of the above

**Ans:-** (ii) Delta

**Hint:-** Capacitors are always connected in **delta** since the capacitors of the capacitor required is one-third of that required for star connection.

**199. In a 3-phase system, the line losses are**

- (i) Directly proportional to  $\cos \phi$   
(ii) Inversely proportional to  $\cos \phi$   
(iii) Inversely proportional to  $\cos^2 \phi$   
(iv) None of the above

**Ans:-** (iii) Inversely proportional to  $\cos^2 \phi$

**Hint:-**Line current  $I_L = \frac{P}{\sqrt{3}V_L \cos\phi}$

Since the losses are proportional to the square of  $I_L$ , it follows that line losses are proportional to  $1/\cos^2\phi$

**200. A synchronous condenser improves p.f. by taking**

- (i) Lagging kVAR
- (ii) Leading kVAR
- (iii) Both (i) and (ii)
- (iv) None of the above

**Ans:-** (ii) Leading kVAR